



Hc

☐ Search Result - Print
Format

[< Back to Pre](#)

Key: IEEE JNL = IEEE Journal or Magazine, IEE JNL = IEE Journal or Magazine, IEEE CNF = IEEE Conference, IEE CNF = IEE Conference, IEEE STD = IEEE Standard

1. **TCP position tolerances in joint torque minimizations**
Grahn, S.; Flisberg, P.; Johansson, G.; Lindberg, P.O.; Larsson, T.;
Intelligent Robots and Systems, 1998. Proceedings., 1998 IEEE/RSJ
International Conference on
Volume 2, 13-17 Oct. 1998 Page(s):800 - 805 vol.2
IEEE CNF
2. **A numerical approach for planning robot trajectories considering collision avoidance**
Van De Logt, G.; Odekerken, F.-J.;
Systems, Man, and Cybernetics, 1996., IEEE International Conference on
Volume 2, 14-17 Oct. 1996 Page(s):1501 - 1507 vol.2
IEEE CNF
3. **Learning accurate path control of industrial robots with joint elasticity**
Lange, F.; Hirzinger, G.;
Robotics and Automation, 1999. Proceedings. 1999 IEEE International
Conference on
Volume 3, 10-15 May 1999 Page(s):2084 - 2089 vol.3
IEEE CNF
4. **Development and comparison of search algorithms for robot motion planning in the configuration space**
Akutsu, T.; Yaoi, S.; Sato, K.; Enomoto, S.;
Intelligent Robots and Systems '91. 'Intelligence for Mechanical Systems,
Proceedings IROS '91. IEEE/RSJ International Workshop on
3-5 Nov. 1991 Page(s):429 - 434 vol.2
IEEE CNF
5. **Cascaded control concept of a robot with two degrees of freedom driven by four artificial pneumatic muscle actuators**
Hildebrandt, A.; Sawodny, O.; Neumann, R.; Hartmann, A.;
American Control Conference, 2005. Proceedings of the 2005
8-10 June 2005 Page(s):680 - 685 vol. 1
IEEE CNF
6. **Contact observation of interactive surgical robotics systems**
Hein, A.; Lueth, T.C.; Hommel, G.;
Intelligent Robots and Systems, 1999. IROS '99. Proceedings. 1999 IEEE/RSJ
International Conference on
Volume 2, 17-21 Oct. 1999 Page(s):733 - 739 vol.2
IEEE CNF
7. **Time optimal manipulator control for sensor guided grasping of moving objects**
Kondak, K.; Binner, S.; Hommel, G.; Neumann, M.;
Intelligent Robots and Systems, 2001. Proceedings. 2001 IEEE/RSJ International

Conference on
Volume 4, 29 Oct.-3 Nov. 2001 Page(s):1912 - 1917 vol.4
IEEE CNF

Indexed by
 Inspec

© Copyright 2006 IEEE – All Right